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NTE1729

Integrated Circuit

Pulse Width Modulator (PWM) Control Circuit

Description:

The NTE1729 is an inverter control unit in a 16-Lead DIP type package which provides all the control circuitry for PWM type switching regulators. Included in this device is the voltage reference, dual error amplifiers, oscillator, pulse width modulator, pulse steering flip flop, dual alternating output switches, and dead time control.

Features:

- Complete PWM Power Control Circuit
- Adjustable Dead Time: 0 to 100%
- No Double Pulsing of Same Output during Load Transient Condition
- Dual Error Amplifiers have Wide Common Mode Input Voltage Capability: $-0.3V$ to $V_{CC} - 2V$
- Circuit Architecture Provides Easy Synchronization
- Uncommitted Outputs for 250mA Sink or Source
- With Miss-Operation Prevention Circuit for Low Level Supply Voltage

Absolute Maximum Ratings: ($T_A = +25^\circ C$ unless otherwise specified)

Supply Voltage, V_{CC}	41V
Error Amplifier Input Voltage, V_{ICM}	$V_{CC} + 0.3V$
Output Voltage, V_{CER}	41V
Total Power Dissipation ($T_A = +25^\circ C$), P_T	1000mW
Operating Temperature Range, T_{opr}	-20° to $+85^\circ C$
Storage Temperature Range, T_{stg}	-65° to $+150^\circ C$

Recommended Operating Conditions:

Parameter	Symbol	Min	Typ	Max	Unit
Supply Voltage	V_{CC}	7	—	40	V
Output Voltage	V_{CER}	-0.3	—	40	V
Output Current	I_C	—	—	200	mA
Error Amplifier Sink Current	I_{OAMP}	—	—	-0.3	mA
Timing Capacitor	C_T	0.47	—	10000	nF
Timing Resistance	R_T	1.8	—	500	k Ω
Oscillation Frequency	f_{osc}	1	—	300	kHz
Operating Temperature	T_{opt}	-20	—	$+70$	°C

Electrical Characteristics: ($V_{CC} = +15V$, $f = 10\text{kHz}$, $-20^\circ \leq T_A \leq +70^\circ\text{C}$, unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit	
Reference Section							
Output Voltage	V_{ref}	$I_{ref} = 1\text{mA}$, $T_A = +25^\circ\text{C}$	4.75	5.0	5.25	V	
Line Regulation	REG_{IN}	$7V \leq V_{CC} \leq 40V$, $I_{ref} = 1\text{mA}$, $T_A = +25^\circ\text{C}$	–	8	25	mV	
Load Regulation	REG_L	$1\text{mA} \leq I_{ref} \leq 10\text{mA}$, $T_A = +25^\circ\text{C}$	–	1	15	mV	
Temperature Coefficient	V_{ref}	$-20^\circ \leq T_A \leq +85^\circ\text{C}$, $I_{ref} = 1\text{mA}$	–	0.01	0.03	%/ $^\circ\text{C}$	
Short-Circuit Output Current	I_{short}	$V_{ref} = 0$, $T_A = +25^\circ\text{C}$, Note 2	–	50	–	mA	
Oscillator Section							
Frequency	f_{osc}	$C_T = 0.01\mu\text{F}$, $R_T = 12\text{k}\Omega$, $T_A = +25^\circ\text{C}$	–	10	–	kHz	
Standard Deviation of Frequency		$7V \leq V_{CC} \leq 40V$, C_T , R_T , Const., $T_A = +25^\circ\text{C}$, Note 1	–	10	–	%	
Frequency Change with Temperature		$0^\circ \leq T_A \leq +70^\circ\text{C}$, $C_T = 0.01\mu\text{F}$, $R_T = 12\text{k}\Omega$	–	1	2	%	
Frequency Change with Voltage		$7V \leq V_{CC} \leq 40V$, $C_T = 0.01\mu\text{F}$, $R_T = 12\text{k}\Omega$, $T_A = +25^\circ\text{C}$	–	–	1	%	
Dead-Time Control Section							
Input Bias Current		$0 \leq V_I \leq 5.25V$	–	–2	–10	μA	
Maximum Duty Cycle (Each Output)		$V_I = 0$	45	49	–	%	
Input Threshold Voltage	V_{th}	Zero Duty Cycle	–	3.0	3.3	V	
		Maximum Duty Cycle	0	–	–	V	
Error Amplifier Section							
Input Offset Voltage	V_{IO}	$V_{OAMP} = 2.5V$	–	2	10	mV	
Input Offset Current	I_{IO}	$V_{OAMP} = 2.5V$	–	25	250	nA	
Input Bias Current		$V_{OAMP} = 2.5V$	–	0.2	1.0	mA	
Common Mode Input Voltage	Low	V_{ICM}	$7V \leq V_{CC} \leq 40V$	–0.3	–	–	V
				V_{CC}^{-2}	–	–	V
Open-Loop Voltage Amplification	A_V	$V_{OAMP} = 0.5V$ to $3.5V$, $T_A = +25^\circ\text{C}$	60	80	–	dB	
Unity Gain Bandwidth		$T_A = +25^\circ\text{C}$	500	830	–	kHz	
Common Mode Rejection Ratio	$CMRR$	$V_{CC} = 40V$, $T_A = +25^\circ\text{C}$	65	80	–	dB	
Output Sink Current		$V_{OAMP} = 0.7V$	0.3	0.7	–	mA	
Output Source Current		$V_{OAMP} = 3.5V$	–2	–10	–	mA	
PWM Section							
Input Threshold Voltage		Zero Duty Cycle	–	4.0	4.5	V	
Input Sink Current		$V_{(Pin3)} = 0.7V$	0.3	0.7	–	mA	
Output Section							
Collector Cutoff Current	I_{CER}	$V_{CE} = 40V$, $V_{CC} = 40V$	–	2	100	μA	
Emitter Cutoff Current		$V_{CC} = V_C = 40V$	–	–	–100	μA	
Collector Saturation Voltage	$V_{CE(sat)}$	$I_C = 200\text{mA}$, $V_E = 0$, Common Emitter	0	0.95	1.3	V	
	$V_{CE(on)}$	$I_E = 200\text{mA}$, $V_C = 15V$, Emitter Follower	–	1.6	2.5	V	

Electrical Characteristics (Cont'd): ($V_{CC} = +15V$, $f = 10\text{kHz}$, $-20^\circ \leq T_A \leq +70^\circ\text{C}$, unless otherwise specified)

Parameter	Symbol	Test Conditions		Min	Typ	Max	Unit	
Output Section (Cont'd)								
Output Voltage Rise Time	Common Emitter	t_r	$V_{CC} = 15V$, $R_L = 150\Omega$, $I_O = 100\text{mA}$, $T_A = +25^\circ\text{C}$	—	100	200	ns	
	Emitter Follower			—	100	200	ns	
Output Voltage Fall Time	Common Emitter	t_f		—	70	200	ns	
	Emitter Follower			—	70	200	ns	
Total Device								
Standby Current	$I_{CC(S.B.)}$	$V_{CC} = 15V$, all other inputs and outputs open		—	8.0	12.5	mA	
Bias Current	$I_{CC(B.I.)}$	$V_{(Pin4)} = 2V$		—	10	—	mA	

Note 1. Standard deviation is a measure of the statistical distribution about the mean as derived from the formula:

$$\alpha = \sqrt{\frac{\sum_{n=1}^N (X_n - \bar{X})^2}{N-1}}$$

Calculation expression of frequency is as follows:

$$f_{osc} = \frac{1}{0.817 R_T \bullet C_T + 1.42 \bullet 10^{-6}} \text{ (Hz)} \quad [R_T] = \Omega, [C_T] = F$$

Note 2. Maximum duration of short-circuit condition is 1sec (non-repetitive).



